

FIG. 1

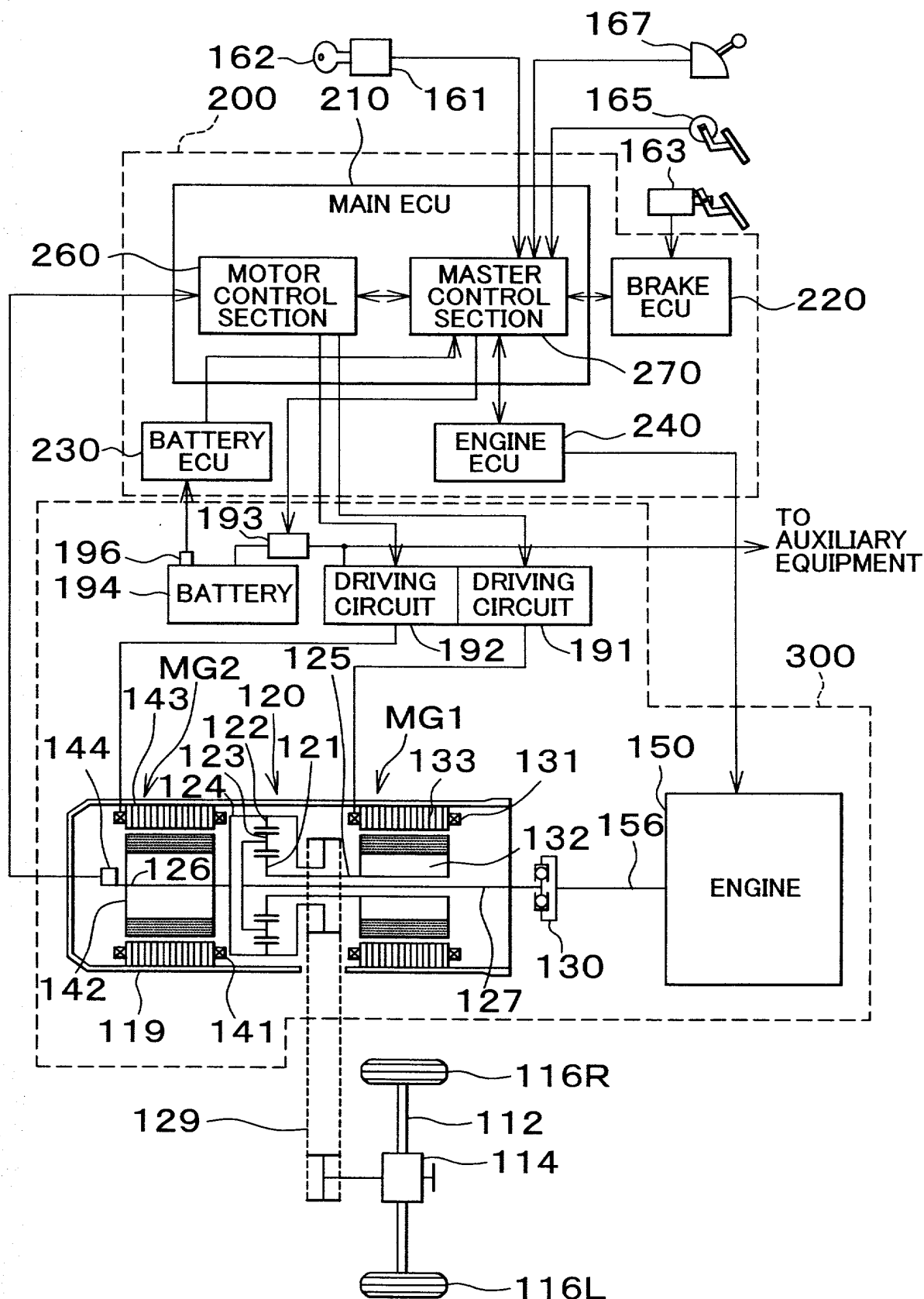


FIG. 3

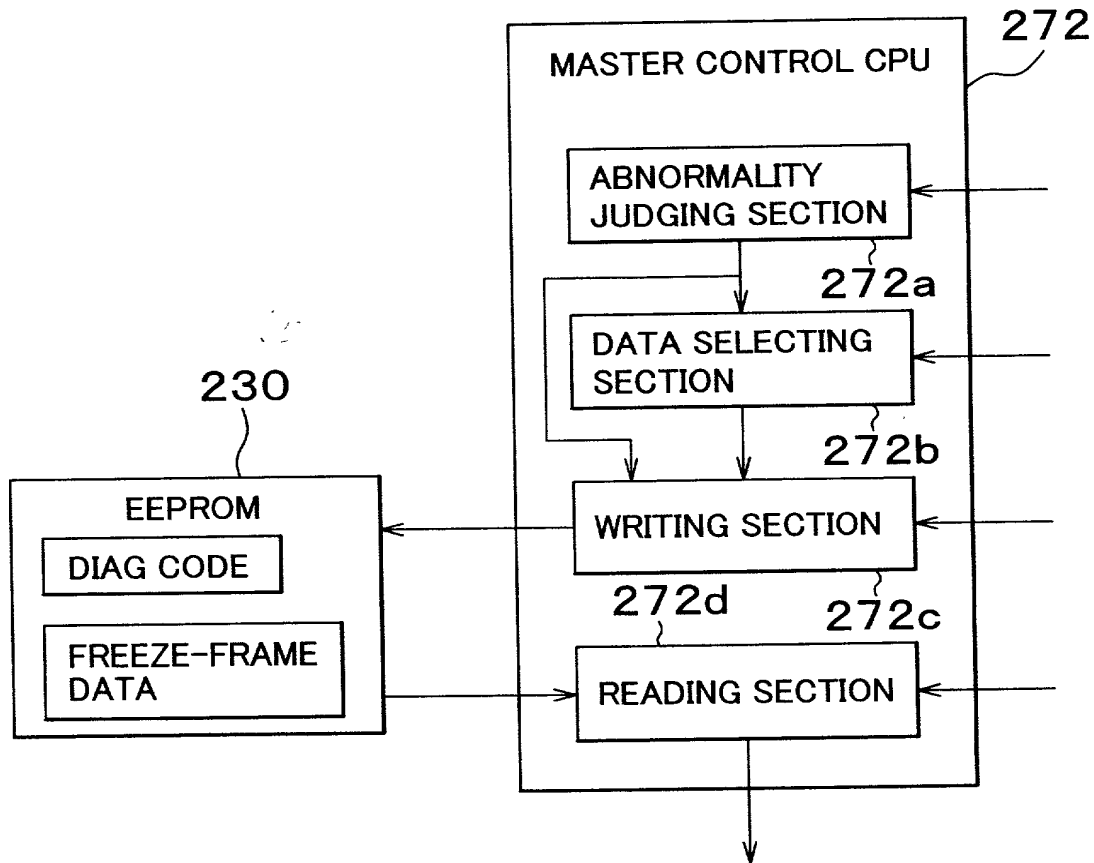


FIG. 4

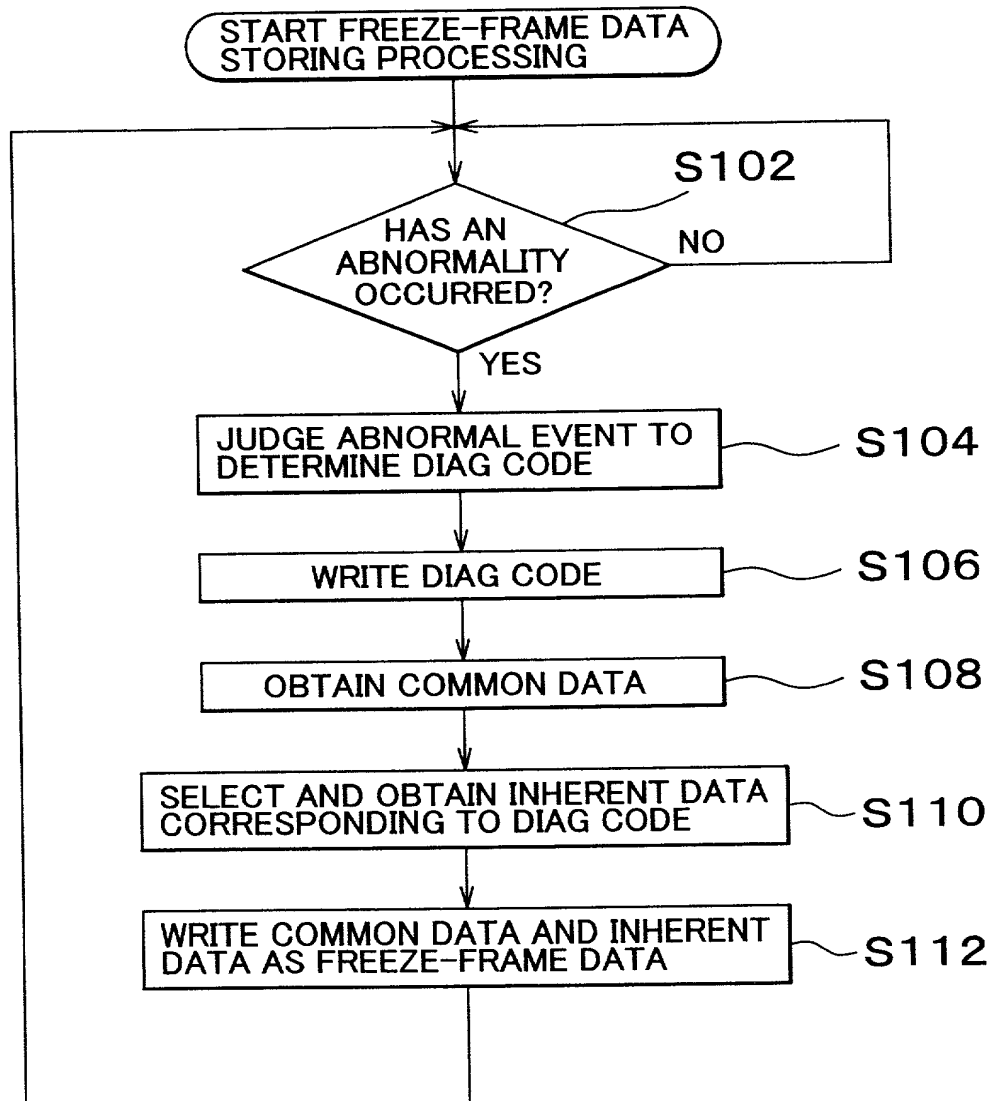


FIG. 5A



FIG. 5B

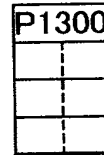


FIG. 5C

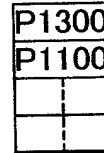


FIG. 5D

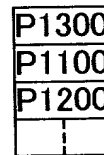


FIG. 5E

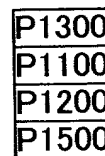


FIG. 6A

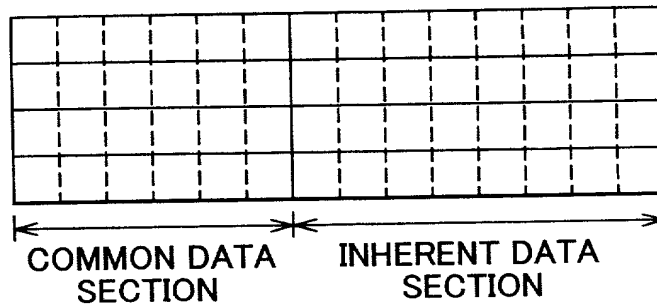


FIG. 6B

FRAME1

$\alpha t1$	$\beta t1$	$\gamma t1$	$at1$	$bt1$	$ct1$	$dt1$

FIG. 6C

FRAME1

FRAME2

$\alpha t1$	$\beta t1$	$\gamma t1$	$at1$	$bt1$	$ct1$	$dt1$
$\alpha t2$	$\beta t2$	$\gamma t2$	$et2$	$ft2$	$gt2$	$ht2$

FIG. 6D

FRAME1

FRAME2

FRAME3

$\alpha t1$	$\beta t1$	$\gamma t1$	$at1$	$bt1$	$ct1$	$dt1$
$\alpha t2$	$\beta t2$	$\gamma t2$	$et2$	$ft2$	$gt2$	$ht2$
$\alpha t3$	$\beta t3$	$\gamma t3$	$it3$	$jt3$	$kt3$	$lt3$

FIG. 6E

FRAME1

FRAME2

FRAME3

FRAME4

$\alpha t1$	$\beta t1$	$\gamma t1$	$at1$	$bt1$	$ct1$	$dt1$
$\alpha t2$	$\beta t2$	$\gamma t2$	$et2$	$ft2$	$gt2$	$ht2$
$\alpha t3$	$\beta t3$	$\gamma t3$	$it3$	$jt3$	$kt3$	$lt3$
$\alpha t4$	$\beta t4$	$\gamma t4$	$mt4$	$nt4$	$ot4$	$pt4$

FIG. 7A-1

PID=0,FRAME NUMBER=1

$\alpha t1$	$\beta t1$	$\gamma t1$	at1
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FIG. 7A-2

PID=1,FRAME NUMBER=1

bt1	ct1	dt1		
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FIG. 7A-3

PID=0,FRAME NUMBER=2

$\alpha t2$	$\beta t2$	$\gamma t2$	et2
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FIG. 7B-1

PID=1,FRAME NUMBER=2

ft2	gt2	ht2		
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FIG. 7B-2

PID=0,FRAME NUMBER=3

$\alpha t3$	$\beta t3$	$\gamma t3$	it3
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FIG. 7C-1

PID=1,FRAME NUMBER=3

jt3	kt3	lt3		
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FIG. 7C-2

PID=0,FRAME NUMBER=4

$\alpha t4$	$\beta t4$	$\gamma t4$	mt4
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FIG. 7C-3

PID=1,FRAME NUMBER=4

nt4	ot4	pt4		
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FIG. 8

FRAME1	$\alpha t1$	$\beta t1$	$\gamma t1$	at1	bt1	ct1	dt1
FRAME2	$\alpha t2$	$\beta t2$	$\gamma t2$	ft2	ht2		
FRAME3	$\alpha t3$	$\beta t3$	$\gamma t3$	it3	kt3	lt3	
FRAME4	$\alpha t4$	$\beta t4$	$\gamma t4$	mt4	nt4		

FIG. 9

FRAME1	$\alpha t1$	$\beta t1$	$\gamma t1$	at1	bt1	ct1	dt1
FRAME2	$\alpha t2$	$\beta t2$	$\gamma t2$	et2	ft2	ht2	
FRAME3	$\alpha t3$	$\beta t3$	$\gamma t3$	it3	kt3	lt3	
FRAME4	$\alpha t4$	$\beta t4$	$\gamma t4$	mt4	nt4	pt4	

FIG. 10

FRAME1	$\alpha t1$	$\beta t1$	$\gamma t1$	at1	bt1	ct1	dt1
FRAME2	$\alpha t2$	$\beta t2$	$\gamma t2$	ft2	ht2		
FRAME3	$\alpha t3$	$\beta t3$	$\gamma t3$	it3	kt3	lt3	
FRAME4	$\alpha t4$	$\beta t4$	$\gamma t4$	mt4	nt4		

FIG. 11

FRAME1	$\alpha t1$	$\beta t1$	$\gamma t1$	at1	bt1	ct1	dt1
FRAME2	$\alpha t2$	$\beta t2$	$\gamma t2$	ft2			ht2
FRAME3	$\alpha t3$	$\beta t3$	$\gamma t3$	it3	kt3	lt3	
FRAME4	$\alpha t4$	$\beta t4$	$\gamma t4$		mt4	nt4	

FIG. 12

